

426(5): New Formulation of the Hamilton Equations in Special Relativity

Begin by summarizing the equations of n theory:

$$\mathcal{L} = p_1 \dot{r}_1 - H \quad (1)$$

$$p_1 \dot{r}_1 = m(r_1) \gamma mc^2 - \frac{mc^2}{\gamma} \quad (2)$$
$$= \frac{p_1^2 c^2}{\gamma mc^2} - H$$

From fundamentals:

$$p_1 = \frac{\partial \mathcal{L}}{\partial \dot{r}_1} = - \frac{\partial H}{\partial \dot{r}_1} \quad (3)$$

and

$$\frac{\partial}{\partial r_1} \left(m(r_1) \gamma mc^2 - \frac{mc^2}{\gamma} \right) = 0 \quad (4)$$

Here:

$$H = \gamma m(r_1) mc^2 - \frac{nMG}{r_1} \quad (5)$$

and

$$\mathcal{L} = - \frac{mc^2}{\gamma} + \frac{nMG}{r_1} \quad (6)$$

where

$$\gamma = \left(m(r_1) - \frac{v_1^2}{c^2} \right)^{-1/2} \quad (7)$$

Using: $v_1^2 = \dot{r}_1^2 + r_1^2 \dot{\phi}^2$ (8)

it follows as in KFT 425 that:

$$\frac{dm(r_1)}{dr_1} = - \frac{2L^2}{\gamma^3 c^2 m^2 r_1^3} \left(\frac{1 - \gamma^2 m(r_1)}{1 + \gamma^2 m(r_1)} \right) \quad (9)$$

where:

2)

$$L = \gamma r_1^2 m \dot{\phi} - (10)$$

the conserved angular momentum of n theory. Here:

$$r_1 = \frac{r}{m(r)^{1/2}} - (11)$$

In the limit of special relativity:

$$m(r_1) \rightarrow 1, \quad \frac{dm(r_1)}{dr_1} \rightarrow 0 - (12)$$

and

$$\gamma \rightarrow \left(1 - \frac{v_N^2}{c^2}\right)^{-1/2} - (13)$$

where the Newtonian velocity is defined by:

$$v_N^2 = \dot{r}^2 + r^2 \dot{\phi}^2 - (14)$$

in frame (r, ϕ) .

the flat space of special relativity is approached as:

$$r_1^3 \rightarrow \infty - (15)$$

so in eq. (9):

$$\frac{dm(r_1)}{dr_1} \rightarrow 0 - (16)$$

In the limit of S.R. eq. (4) becomes:

$$\frac{d\gamma}{dr} = \frac{d}{dr} \left(\frac{1}{\gamma} \right) - (17)$$

This is true if $\frac{d\gamma}{dr} = \frac{d}{dr} \left(\frac{1}{\gamma} \right) = 0 - (18)$

i.e.

$$\boxed{\frac{dv_N}{dr} = 0} - (19)$$

3) Eq. (19) follows immediately in Hamiltonian dynamics if the canonically conjugate generalized coordinates are defined as:

$$p = m v_N, \quad q = r \quad (20)$$

The canonically conjugate variables are independent so:

$$\frac{\partial p}{\partial q} = 0 \quad (21)$$

which is Eq. (19). The latter means that:

$$\frac{d}{dr} (\dot{r}^2 + r^2 \dot{\phi}^2) = 0 \quad (22)$$

i.e.

$$\frac{d}{dt} (\dot{r}^2 + r^2 \dot{\phi}^2) = 0 \quad (23)$$

using

$$\frac{df}{dr} = \frac{df}{dt} \frac{dt}{dr} \quad (24)$$

Eq. (23) constrains ϕ . From Eckardt equation for special relativity:

$$\frac{dH}{dt} = 0 \quad (25)$$

$$\frac{dL}{dt} = 0 \quad (26)$$

where

$$H = \gamma m c^2 - \frac{m M G}{r} \quad (27)$$

$$L = \gamma m r^2 \dot{\phi} \quad (28)$$

Eq. (23), (27) and (28) must be solved simultaneously

4) Eqs. (22) and (27) give:

$$\frac{\partial H}{\partial r} = \frac{-2mG}{r^3} \quad (29)$$

So

$$\dot{p} = -\frac{\partial H}{\partial r} = \frac{2mG}{r^3} \quad (30)$$

Eqs. (23) and (28) give:

$$\frac{dL}{dt} = \gamma \frac{d}{dt}(mr^2\dot{\phi}) = 0 \quad (31)$$

because

$$\frac{d\gamma}{dt} = 0 \quad (32)$$

W. of choice (28):

$$H = mc^2 \left(1 - \frac{p^2}{m^2 c^2} \right)^{-1/2} - \frac{2mG}{r} \quad (33)$$

where

$$p = m v_N \quad (34)$$

So

$$\dot{r} = \frac{\partial H}{\partial p} = \frac{\gamma^3 p}{m} = \gamma^3 v_N \quad (35)$$

It follows that:

$$m\ddot{r} = 2\gamma^3 \dot{v}_N = -\frac{2mG}{r^2} \quad (36)$$

Finally we:

$$\frac{d}{dt}(\gamma m v_N) = 2\gamma^3 \dot{v}_N = -\frac{2mG}{r^2} \quad (37)$$

5) Eq. (37) is the equation of special relativity used in previous work to produce a necessary ellipse. The choice (20) ensures that:

$$\frac{dp}{dr} = 0 \quad - (38)$$

and

$$\frac{dV_N}{dr} = 0 \quad - (39)$$

The Hamiltonian equations (22) and (23) give new dynamics, and can be integrated numerically, and both the Lagrangian and Hamiltonian methods give eq. (37).

Using the choice:

$$p_\phi = L, \quad r_\phi = \dot{\phi} \quad - (40)$$

we have:

$$\dot{L} = \dot{p}_\phi = -\frac{\partial H}{\partial \phi} = 0 \quad - (41)$$

So the angular momentum is a constant of motion. The relativistic momentum for eq. (37) is:

$$\underline{p} = \gamma m \underline{v}_N \quad - (42)$$

so the magnitude of \underline{L} is:

$$|\underline{L}| = |\underline{r} \times \underline{p}| = \gamma m r^2 \dot{\phi} \quad - (43)$$

using:

$$\underline{v} = \dot{r} \underline{e}_r + r \dot{\phi} \underline{e}_\phi \quad - (44)$$

and

$$\underline{r} = r \underline{e}_r \quad - (45)$$

In the Hamilton-Jacobi formalism:

$$L = \frac{dS_\phi}{d\phi} = \text{constant} \quad - (46)$$

so

$$\boxed{\frac{dS_\phi}{d\phi} = \gamma m r^2 \dot{\phi}} \quad - (47)$$

and the action S_ϕ can be found by integration.
Similarly the action S_r can be found as in the
next note.
