

426(1): Other Fundamental Equations of the Euler Lagrange Hamilton Dynamics

The use of these equations will involve further information to a theory. For example the angular momentum is defined by:

$$L = \frac{\partial \mathcal{L}}{\partial \dot{\phi}} \quad (1)$$

where \mathcal{L} is the Lagrangian:

$$\mathcal{L} = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\phi}^2) + \frac{mMG}{r} \quad (2)$$

on the Newtonian level. Using the Euler Lagrange equations:

$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{\phi}} = \frac{\partial \mathcal{L}}{\partial \phi} \quad (3)$$

it follows that

$$\dot{L} = \frac{dL}{dt} = 0 \quad (4)$$

In Hamilton dynamics:

$$\dot{L} = \dot{p}_{\phi} = - \frac{\partial H}{\partial \phi} = 0 \quad (5)$$

where the Hamiltonian is:

$$H = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\phi}^2) - \frac{mMG}{r} \quad (6)$$

so

$$\dot{L} = \frac{\partial \mathcal{L}}{\partial \phi} = - \frac{\partial H}{\partial \phi} = 0 \quad (7)$$

and

$$\dot{\phi} = \frac{\partial H}{\partial L} \quad (8)$$

The first Evans Eckart equation is defined in Euler/Lagrange/Hamilton dynamics as:

$$\frac{dH}{dt} = \frac{\partial H}{\partial t} = - \frac{\partial \mathcal{L}}{\partial t} = 0 \quad (9)$$

The use of the Hamilton equations shows that the Euler-Lagrange equations are:

$$\frac{dH}{dt} = - \frac{\partial L}{\partial t} = 0 \quad (10)$$

$$\frac{dL}{dt} = - \frac{\partial H}{\partial \phi} = 0 \quad (11)$$

where

$$\dot{\phi} = \frac{\partial H}{\partial L} \quad (12)$$

Eqns. (10) to (12) are general, and can be used in theory.

On the Newtonian level:

$$L = \frac{\partial L}{\partial \dot{\phi}} = m r^2 \dot{\phi} \quad (13)$$

the Hamiltonian is:

$$H = \frac{1}{2} m \left(\dot{r}^2 + \frac{L^2}{m^2 r^2} \right) \quad (14)$$

$$\frac{\partial H}{\partial L} = \frac{m L}{m^2 r^2} = \dot{\phi} \quad (15)$$

so

Q.E.D. In special relativity the Hamiltonian canonical

variables are:

$$p_r = \gamma m \dot{r}, \quad \dot{r} = \frac{p_r}{\gamma m} \quad (16)$$

$$p_\phi = \gamma m r \dot{\phi}, \quad \dot{\phi} = \frac{p_\phi}{\gamma m r} \quad (17)$$

and

$$\vec{p} = p_r \frac{\mathbf{e}_r}{r} + p_\phi \frac{\mathbf{e}_\phi}{r} \quad (18)$$

The Hamilton equations are:

$$\dot{p} = -\frac{\partial H}{\partial q} \quad (19)$$

$$\dot{q} = \frac{\partial H}{\partial p} \quad (20)$$

$$H = p\dot{q} - \mathcal{L} \quad (21)$$

where
 in generalized coordinate coordinates p and q .

Therefore:

$$\dot{r} = \frac{\partial H}{\partial p_r} \quad (22)$$

$$r\dot{\phi} = \frac{\partial H}{\partial p_\phi} \quad (23)$$

and
 in the plane polar system (r, ϕ) in this system:

$$p = \gamma m \frac{v}{c} \quad (24)$$

$$\underline{v} = \dot{r} \underline{e}_r + r\dot{\phi} \underline{e}_\phi \quad (25)$$

$$v^2 = v_r^2 + v_\phi^2 \quad (26)$$

$$= \dot{r}^2 + r^2 \dot{\phi}^2$$

The Hamiltonian of special relativity is:

$$H = \gamma mc^2 - \frac{m\phi}{c} \quad (27)$$

$$\gamma = \left(1 - \frac{v^2}{c^2}\right)^{-1/2} \quad (28)$$

It follows that:

$$\dot{q} = \frac{\partial H}{\partial p} = \frac{\partial H}{\partial v} \frac{\partial v}{\partial p} \quad (29)$$

4) where $\underline{p} = m \underline{v}_N = p_r \underline{e}_r + p_\phi \underline{e}_\phi$ - (30)

so $v_N^2 = \frac{p^2}{m^2} = \frac{1}{m^2} (p_r^2 + p_\phi^2)$ - (31)

and $p = \frac{|p|}{\gamma} = \gamma m v_N$ - (32)

$$= m v_N \left(1 - \frac{v_N^2}{c^2}\right)^{-1/2}$$

It follows that:

$$\frac{dp}{dv_N} = m \left(\gamma + v_N \frac{d}{dv_N} \left(1 - \frac{v_N^2}{c^2}\right)^{-1/2} \right)$$

$$= m \left(\gamma + \gamma^3 \frac{v_N^2}{c^2} \right)$$

$$= \gamma^3 m \left(\frac{1}{\gamma^2} + \frac{v_N^2}{c^2} \right)$$

$$= m \gamma^3$$

S. Q. Hamilton's equation (20) produces:

$$\dot{q} = \frac{1}{m \gamma^3} \frac{\partial H}{\partial v_N} \quad - (34)$$

where $\frac{\partial H}{\partial v_N} = m \gamma^3 v_N$ - (35)

so $\dot{q} = v_N$ - (36)

Q.E.D.

It follows that:

$$\dot{\underline{q}} = \dot{q}_r \underline{e}_r + \dot{q}_\phi \underline{e}_\phi \quad - (37)$$

$$= \dot{r} \underline{e}_r + r \dot{\phi} \underline{e}_\phi$$

so

$$\dot{q}_r = \dot{r} \quad \dots - (38)$$

and

$$\dot{q}_\phi = r\dot{\phi} \quad \dots - (39)$$

Q.E.D.

Having defined the relationships at the Newtonian
and special relativistic levels, it is now possible to
produce extra information in a theory. This information
is missing from a pure Lagrangian analysis but provides
many new insights

For example:

$$H = p\dot{q} - L \quad \dots - (40)$$

can be used with:

$$\frac{\partial H}{\partial p} = \dot{q} \quad \dots - (41)$$

and

$$\frac{\partial H}{\partial q} = -\dot{p} \quad \dots - (42)$$

Eqs. (40) and (42) produce:

$$\dot{p} = \frac{\partial H}{\partial q} = \frac{\partial(p\dot{q})}{\partial q} - \frac{\partial L}{\partial q} \quad \dots - (43)$$

and this equation has already been used in UFT425

produce a new equation for $dm(r_i)/dr_i$.

Eqs. (40) and (41) produce:

$$\dot{q} = \frac{\partial H}{\partial p} = \frac{\partial(p\dot{q})}{\partial p} - \frac{\partial L}{\partial p} \quad \dots - (44)$$

and eq. (44) produces new information in a theory.

Eq. (44) is:

$$\dot{q}_i = \frac{\partial H}{\partial p} = \dot{V} + p \frac{\partial \dot{V}}{\partial p} - \frac{\partial L}{\partial p} \quad (45)$$

Using eq. (41):

$$\frac{\partial L}{\partial p} = p \frac{\partial \dot{V}}{\partial p} \quad (46)$$

This is a new equation of motion of general use in classical dynamics. It can be used to find new

information about the level. Eq. (46) can be taken as follows. On a Newtonian level:

$$L = \frac{p^2}{2m} + \frac{2mG}{r} \quad (47)$$

$$\frac{\partial L}{\partial p} = v_N \quad (48)$$

We have:

$$p = mv_N, \quad \dot{q}_i = v_N \quad (49)$$

$$\frac{\partial p}{\partial \dot{q}_i} = m \quad (50)$$

It follows that:

$$p \frac{\partial \dot{q}_i}{\partial p} = v_N \quad (51)$$

so eq. (46) is true on a Newtonian level, Q.E.D.

In special relativity:

$$L = -mc^2 \left(1 - \frac{p^2}{m^2 c^2} \right)^{1/2} + \frac{2mG}{r} \quad (52)$$

$$\frac{\partial L}{\partial p} = \frac{\partial L}{\partial v_N} \frac{dv_N}{dp} = \frac{1}{\gamma^3} \frac{\partial L}{\partial v_N} \quad (53)$$

so

$$\frac{\partial \mathcal{L}}{\partial v_N} = \gamma m v_N = p \quad - (54)$$

so

$$\frac{\partial \mathcal{L}}{\partial p} = \frac{v_N}{\gamma^3} \quad - (55)$$

Similarly:

$$\frac{\partial \dot{q}_V}{\partial p} = \frac{\partial \dot{q}_V}{\partial v_N} \frac{\partial v_N}{\partial p} = \frac{1}{m \gamma^3} \quad - (56)$$

and

$$p = \gamma m v_N \quad - (57)$$

so

$$p \frac{\partial \dot{q}_V}{\partial p} = \frac{v_N}{\gamma^3} = \frac{\partial \mathcal{L}}{\partial p} \quad - (58)$$

Q.E.D.

We are now ready to develop these equations in n theory and to develop a Hamilton Jacobi formalism of n theory.

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