

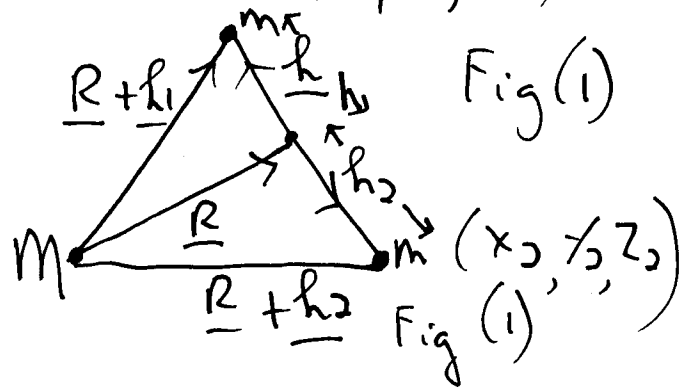
370(8) : Extension of the Dumbbell Model in Notes and Protocol by Hoffmann.  $(x_1, y_1, z_1)$

we have:

$$x_1 = |\underline{R} + \underline{h}_1| \sin \theta_1 \cos \phi_1 \quad - (1)$$

$$y_1 = |\underline{R} + \underline{h}_1| \sin \theta_1 \sin \phi_1 \quad - (2)$$

$$z_1 = |\underline{R} + \underline{h}_1| \cos \theta_1 \quad - (3)$$



and

$$x_2 = |\underline{R} + \underline{h}_2| \sin \theta_2 \cos \phi_2 \quad - (4)$$

$$y_2 = |\underline{R} + \underline{h}_2| \sin \theta_2 \sin \phi_2 \quad - (5)$$

$$z_2 = |\underline{R} + \underline{h}_2| \cos \theta_2 \quad - (6)$$

in spherical polar coordinates.

The kinetic energy is:

$$T = \frac{1}{2} m \left( \dot{x}_1^2 + \dot{y}_1^2 + \dot{z}_1^2 \right) + \left( \dot{x}_2^2 + \dot{y}_2^2 + \dot{z}_2^2 \right) \quad - (7)$$

$$= \frac{1}{2} m \left( \dot{r}_1^2 + r_1^2 \dot{\theta}_1^2 + r_1^2 \dot{\phi}_1^2 \sin^2 \theta_1 \right) + \left( \dot{r}_2^2 + r_2^2 \dot{\theta}_2^2 + r_2^2 \dot{\phi}_2^2 \sin^2 \theta_2 \right) \quad - (8)$$

If the two masses  $m$  are gravitationally attracted to the mass  $M$ , then the potential energy is

$$U = - \frac{mMg}{r_1} - \frac{mMg}{r_2} \quad - (9)$$

Here:  $r_1 = |R + h_1| - (10)$

$$r_2 = |R + h_2| - (11)$$

The Lagrangian is:

$$L = T - U - (12)$$

The Lagrangian variables are  $r_1, r_2, \theta_1, \phi_1, \theta_2$  and  $\phi_2$ . So there are six simultaneous equations defined by:

$$\frac{\partial L}{\partial r_1} = \frac{d}{dt} \frac{\partial L}{\partial \dot{r}_1} - (13)$$

$$\frac{\partial L}{\partial r_2} = \frac{d}{dt} \frac{\partial L}{\partial \dot{r}_2} - (14)$$

$$\frac{\partial L}{\partial \theta_1} = \frac{d}{dt} \frac{\partial L}{\partial \dot{\theta}_1} - (15)$$

$$\frac{\partial L}{\partial \phi_1} = \frac{d}{dt} \frac{\partial L}{\partial \dot{\phi}_1} - (16)$$

$$\frac{\partial L}{\partial \theta_2} = \frac{d}{dt} \frac{\partial L}{\partial \dot{\theta}_2} - (17)$$

$$\frac{\partial L}{\partial \phi_2} = \frac{d}{dt} \frac{\partial L}{\partial \dot{\phi}_2} - (18)$$

These equations can be solved for  $r_1(t)$ ,

$r_2(t), \theta_1(t), \phi_1(t), \theta_2(t), \phi_2(t), \dot{r}_1(t), \dot{r}_2(t),$   
 $\dot{\theta}_1(t), \dot{\phi}_1(t), \dot{\theta}_2(t)$  and  $\dot{\phi}_2(t)$

This definition of the problem and its solution takes place in the laboratory frame  $(x, y, z)$  the line joining of two masses can be thought of as a diameter of the earth.

### Check a Concept

If only one mass is being considered, the Lagrangian reduces to:

$$L = \frac{1}{2} m (\dot{r}^2 + r^2 (\dot{\theta}^2 + \dot{\phi}^2 \sin^2 \theta)) - \frac{m M G}{r} \quad (19)$$

and the Lagrange variables are  $r, \theta$  and  $\phi$ . When there are two masses the Lagrange variables become  $r_1, \theta_1, \phi_1, r_2, \theta_2, \phi_2$ .

Having found the motion of  $r_1$  and  $r_2$ , the t.a of  $R, h_1$  and  $h_2$  can also be found from:

$$\underline{r_1} = \underline{R} + \underline{h_1} \quad (20)$$

$$\underline{r_2} = \underline{R} + \underline{h_2} \quad (21)$$