

231(3): Generalization of the Einstein Energy Equation using the Concept of Tetrad as Metric

The fundamental equation derived in note 231(2) is:

$$V_{\mu}^a = g_{\mu}^a = g^{av} g_{\mu\nu} \quad - (1)$$

The tetrad is therefore a mixed index metric linking a and  $\mu$ . Here a and  $\mu$  can be two different representations of the same space, or two different mathematical spaces.

If eq. (1) is written out in full:

$$V_{\mu}^a = g_{\mu}^a = \begin{bmatrix} g^{(1)1} & g^{(1)2} \\ g^{(2)1} & g^{(2)2} \end{bmatrix} \begin{bmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{bmatrix} \quad - (2)$$

where the transverse components are used for identification

in flat 3-D space:

$$\begin{bmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad - (3)$$

so in flat space:

$$V_{\mu}^a = g^{av} g_{\mu\nu} = g^{av} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad - (4)$$

so

$$g^{(1)1} = g^{(1)1} g_{11} \quad - (5)$$

$$g^{(1)2} = g^{(1)2} g_{22} \quad - (6)$$

$$g_1^{(2)} = g^{(2)1} g_{11} \quad - (7)$$

$$g_2^{(2)} = g^{(2)2} g_{22} \quad - (8)$$

If (a) denotes the circular polar basis:

$$g_1^{(1)} = g^{(1)1} = \underline{e}^{(1)} \cdot \underline{i} \quad - (9)$$

$$g_2^{(1)} = g^{(1)2} = \underline{e}^{(1)} \cdot \underline{j} \quad - (10)$$

$$g_1^{(2)} = g^{(2)1} = \underline{e}^{(2)} \cdot \underline{i} \quad - (11)$$

$$g_2^{(2)} = g^{(2)2} = \underline{e}^{(2)} \cdot \underline{j} \quad - (12)$$

In general:

$$V^a = g_{\mu}^a V^{\mu} \quad - (13)$$

i.e.

$$V^a = g_{\mu}^a V^{\mu}, \quad - (14)$$

$$V^a = g^{av} g_{\mu\nu} V^{\mu} = g^{av} V_{\nu} \quad - (15)$$

Therefore the Cartesian tetrad can be defined by:

$$\boxed{V^a = g^{av} V_{\nu}} \quad - (16)$$

in terms of the mixed index metric  $g^{av}$ . The latter is defined by:

$$\boxed{g^{av} = h^a h^{\nu} \underline{e}^a \cdot \underline{e}^{\nu}} \quad - (17)$$

and is symmetric:

$$3) \quad g^{ab} = g_{ab} \quad (18)$$

In eq. (17),  $h^a$  and  $h^{\sim}$  are scaling factors and  $\underline{e}^a$  and  $\underline{e}^{\sim}$  are unit vectors. Eq. (17) is a generalization of eqs. (9) to (12). The unit vector of Minkowski spacetime in the Cartesian representation is:

$$\underline{e}^{\sim} = (\underline{e}^0, \underline{i}, \underline{j}, \underline{k}) \quad (19)$$

and its circular polar representation:

$$\underline{e}^{(a)} = (\underline{e}^{(0)}, \underline{e}^{(1)}, \underline{e}^{(2)}, \underline{e}^{(3)}) \quad (20)$$

where

$$\underline{e}^{(1)} = \frac{1}{\sqrt{2}} (\underline{i} - \underline{j}) \quad (21)$$

$$\underline{e}^{(2)} = \frac{1}{\sqrt{2}} (\underline{i} + \underline{j}) \quad (21a)$$

In this case:  $h^{(a)} = h^{\sim} = 1 \quad (22)$

and  $g^{(a)\sim} = \underline{e}^{(a)} \cdot \underline{e}^{\sim} \quad (23)$

All the equations of differential geometry can be developed with the fundamental definition (23).

If  $\underline{e}^{\sim}$  is defined by eq. (19) then all the dynamical information is defined by  $\underline{e}^{(a)}$ . For example, phase can be added to eqs. (21):

4)

$$\underline{e}^{(1)} = \frac{1}{\sqrt{2}} (\underline{i} - ij) e^{i\phi} \quad - (24)$$

$$\underline{e}^{(2)} = \frac{1}{\sqrt{2}} (\underline{i} + ij) e^{-i\phi} \quad - (25)$$

For the purpose of this note, write the Einstein energy equation as:

$$P^\mu P_\mu = g_\mu^\alpha P^\alpha P^\mu \quad - (26)$$

or:

$$P^\alpha P_\mu = g_\mu^\alpha P^\mu P_\mu = g_\mu^\alpha m^2 c^2$$

$$= g^{\alpha\nu} g_{\mu\nu} m^2 c^2 \quad - (27)$$

From eq. (23):

$$\frac{P^\alpha P_\mu}{m^2 c^2} = \underline{e}^\alpha \cdot \underline{e}^\nu g_{\mu\nu} \quad - (28)$$

which generalizes the Einstein energy equation:

$$P^\mu P_\mu = m^2 c^2 \quad - (29)$$

Eq. (28) is an equation of general relativity,  
 while eq. (29) is an equation of special relativity.